## **Contents**

1	Stru	cture of Machines and Mechanisms	1
	1.1	Machines and Their Role in Modern Production	1
	1.2	Structure of a Machine and its Functional Parts	2
	1.3	Mechanisms. Links and Kinematic Pairs	3
	1.4	Kinematic Chains and Structural Groups.	
		Generation of Mechanisms	10
	1.5	Mechanisms with Excessive Constraints and	
		Redundant Degrees of Movability	17
	1.6	Planar Mechanisms	19
	1.7	Mechanisms with Variable Structure.	
		Strucural Transformations of Mechanisms	24
	1.8	Examples of Structural Analysis of Mechanisms	27
	1.9	Problems	33
2	Geo	ometric Analysis of Mechanisms	41
	2.1	Problems of Geometric Analysis	41
	2.2	Geometric Analysis of Open Kinematic Chains	44
	2.3	Derivation of Equations of Geometric Analysis for	
		Closed Kinematic Chains	52
	2.4	Solution to the Equations of Geometric Analysis	58
	2.5	The Inverse Problem of Geometric Analysis	66
	2.6	Special Features of Geometric Analysis of	
	~ =	Mechanisms with Higher Kinematic Pairs	70
	2.7	Problems	72
3	Kin	ematic and Parametric Analysis of Mechanisms	79
		W. J. A. I. C. C. D. A. C. C.	
	3.1	Kinematic Analysis of Planar Mechanisms	79
	3.2	Kinematic Analysis of Spatial Mechanisms	85
	3.3	Kinematic Analysis of a Mechanism with a Higher Pair	90
	3.4	Kinematics of Mechanisms with Linear Position Functions	93
	3.5	Parametric Analysis of Mechanisms	103
	3.6	Problems	108

	4.1 4.2	Geometric Conditions for Transmission of Forces by Mechanisms  Determination of Forces Acting in Mechanisms by the	121
		Graph-Analytic Method and the Method of Opening Kinematic Chains	128
	4.3	Application of Equilibrium Equations of a Mechanism to its	120
		Kinematic and Parametric Analysis	133
	4.4	General Formulation of the Force Analysis Problem	138
	4.5	Equations of Kinetostatics. Determination of the Resultant	1.42
	4.6	Vector and of the Resultant Moment of Inertia Forces of Links  Solution of the Equations of Kinetostatics	143 147
	4.7	Application of the General Equation of Dynamics for	1.,
		Force Analysis of Mechanisms	152
	4.8	Force Analysis of Mechanisms with Higher Kinematic Pairs	157
	4.9	Problems	158
5	Fric	ction in Mechanisms	175
•	1 110	LIOIT III MECHANISMS	
	5.1	Friction in Kinematic Pairs	175
	5.2	Models of Kinematic Pairs with Friction	178
	5.3	Force Analysis of Mechanisms with Friction	185
	5.4	Problems	194
6	Equ	uations of Motion for a Mechanism with Rigid Links	211
	6.1	Lagrange's Equations of the Second Kind for a	
	0.1	Mechanism with a Single Degree of Movability	211
	6.2	Lagrange's Equations of the Second Kind for	
		Mechanisms with Several Degrees of Movability	216
	6.3	An Example for Derivation of the Equations of Motion of a Mechanism	219
	6.4	Problems	224
	0.1		
7	Dy	namic Characteristics of Mechanisms with Rigid Links	235
	7.1	Internal Vibration Activity of a Mechanism	235
	7.2	Methods of Reduction of Perturbation Moments	237
	7.3 7.4	External Vibration Activity of Mechanisms and Machines  External Vibration Activity of a Rotating Rotor and of a	239
		Rotor Machine	242

	Contents	IJ
7.5	Balancing of Rotors	245
7.6	Vibration Activity of a Planar Mechanism	247
7.7	Loss of Energy due to Friction in a Cyclic Mechanism	252
7.8	Problems	254
8 Dyr	namics of Cycle Machines with Rigid Links	269
8.1	Mechanical Characteristics of Engines	269
8.2	Equations of Motion of a Machine. State of Motion	276
8.3	Determination of the Average Angular Velocity of a	
	Steady-State Motion for a Cycle Machine	278
8.4	Determination of Dynamic Errors and of Dynamic Loads in a	
	Steady-State Motion	280
8.5	Influence of the Engine Dynamic Characteristic on	•
0.0	Steady-State Motions	286
8.6	Starting Acceleration of a Machine	289
8.7 8.8	Braking of a Machine Problems	29 <sup>4</sup> 29:
0.0	1100.4	<b>2</b> 7.
9 Dyi	namics of Mechanisms with Elastic Links	30
9.1	Mechanisms with Elastic Links and Their Dynamic Models	30
9.2	Reduction of Stiffness. Inlet and Outlet Stiffness and	
	Flexibility of a Mechanism	30:
9.3	Reduced Stiffness and Reduced Flexibility of a Mechanism with	
	Several Degrees of Movability	30
9.4	Determination of Reduced Flexibilities with the Help of	
	Equilibrium Equations of a Rigid Mechanism	31
9.5	Some Problems of Kinematic Analysis of Elastic Mechanisms	31
9.6	Dynamic Problems of Elastic Mechanisms	31
9.7	Free and Forced Vibration of Elastic Mechanisms	31
9.8	Problems	32
40 \#	and a selection of the chine and the Chinese Transmission	
	ration of Machines with Elastic Transmission chanisms	32
10	1 Dissipative Forces in Deformable Elements	32
	2 Reduced Stiffness and Reduced Damping Coefficient	33
	3 Steady-State Motion of a Machine with an Ideal Engine.	55
10.	Elastic Resonance	33
10	4 Influence of the Static Characteristic of an Engine on a	ر در
10.	Steady-State Motion	33

X	Contents
Λ	Comems

	ation of a Machine on an Elastic Base.
Vibi	ation Isolation of Machines
11.1	Vibration of the Body of a Machine Mounted on an
	Elastic Base
11.2	Vibration of a Machine in the Resonance Zone.
11.2	Sommerfeld Effect
	Vibration Isolation of Machines
	nents of Dynamics of Machines with Program Control
2 Elei	ments of Dynamics of Machines with Program Control  Basic Principles of Construction of
<b>2 Elei</b> 12.1	ments of Dynamics of Machines with Program Control  Basic Principles of Construction of  Machines with Program Control
<b>2 Elei</b> 12.1 12.2	ments of Dynamics of Machines with Program Control  Basic Principles of Construction of Machines with Program Control Determination of Program Control. Sources of Dynamic Errors
2 Elei 12.1 12.2 12.3	ments of Dynamics of Machines with Program Control  Basic Principles of Construction of Machines with Program Control Determination of Program Control. Sources of Dynamic Errors Closed Feedback Control Systems
2 Elei 12.1 12.2 12.3 12.4	nents of Dynamics of Machines with Program Control
2 Elei 12.1 12.2 12.3 12.4	Basic Principles of Construction of Machines with Program Control  Determination of Program Control. Sources of Dynamic Errors Closed Feedback Control Systems  Effectiveness and Stability of a Closed System