Preface

On behalf of the organizers we would like to welcome all participants to the "Robot Vision 2001" workshop. Our objective has been to bring together researchers in robot vision, and to promote interaction and debate. Participants of the workshop come from Europe, US, the Middle East, the Far East, and of course from New Zealand.

Fifty-two papers were submitted to the workshop, and each paper was thoroughly reviewed by at least three reviewers. Seventeen papers were selected for oral presentation, and seventeen papers were selected for poster presentation. There were no invited technical papers, to give all participants the sense of equal opportunity.

The technical scope of the workshop is very wide, and includes presentations on motion analysis, 3D measurements, calibration, navigation, object recognition, and more. The schedule of the workshop was therefore prepared to allow, in addition to the technical presentation, ample time for discussions and interaction. We hope that interaction among researchers of such different areas, yet all part of robot vision, will result in better understanding and research of the robot vision area.

February 2001   Reinhard Klette, Shmuel Peleg, and Gerald Sommer

Organization

RobVis 2001 was organized by the Center for Image Technology and Robotics (CITR), Tamaki campus, The University of Auckland.

Co-chairs

Reinhard Klette (Auckland, New Zealand)
Shmuel Peleg (Jerusalem, Israel)
Gerald Sommer (Kiel, Germany)

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